Inverse problems for biomedical models of brain tumor evolution

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Motivation

Brain cancer is one of the most common cancer-types worldwide
Reconstruction of initial cell density may aid cancer research

The Fréchet derivative of the cost functional is then given by

 $E'(u) = S(\lambda(x,0) + \mu_1 u(x,0)) + \widetilde{\mu}_2 u(x,0), \quad x \in \Omega,$

where the operator S transforms elements of L^2 -dual to Sobolev

Tumor growth model for brain cancer [J. D. Murray, 2002]

Reaction-diffusion formalism describes the evolution of tumor cell density via two biological phenomena – *diffusion* and *proliferation*:

 $\partial_t u(x,t) - \operatorname{div}(D(x) \nabla u(x,t)) = f(u(x,t)) \quad \text{in } \Omega \times (0,T),$ $D(x) \nabla u(x,t) \cdot n(x) = 0 \quad \text{on } \partial \Omega \times (0,T),$

where D(x) is a diffusion coefficient, f(u) a proliferation function, u(x, t) a normalized *tumor cell density*, and Ω the brain region.

Direct problem – Prediction (well-posed)

Determine a **future state** of a tumor given its current state, i.e., u(x, 0) is known and the model is used to compute u(x, T).

Inverse problem - Source localization (ill-posed)

 $W^{1,2}$ -dual. The descent direction is obtained by *Fletcher–Reeves* conjugate gradient. The *optimal step-length* for updating the initial data estimate u(x,0) is found by solving a sensitivity problem.

Numerical results

Set-up: Brain region Ω and the diffusion coefficient D(x) were based on segmentation of T1-weighted MR images from BraTS2020 dataset. Proliferation function was logistic, i.e., $f(u) = \rho u(1 - u)$. A tumor with Gaussian cell density was planted at a random position in the white matter, and grown according to the model.







Determine an **initial state** of a tumor given its current state, i.e., $\psi(x) \coloneqq u(x, T)$ is known and the model is used to compute u(x, 0). This inverse problem is *ill-posed* since small measurement error may have a profound adverse effect on computational errors.

Main contribution: Solving the inverse problem

We propose an iterative method, where the ill-posed problem is replaced by well-posed problems with multiple regularizing terms.

Sobolev-type cost in non-linear conjugate gradient (NCG)

Given a current state $\psi(x)$ and a set of regularization parameters $m_1, m_2, \mu_1, \mu_2 \ge 0$, one aims to minimize the cost functional

$$\begin{split} E(u) &= m_1 \| u(\cdot, T) - \psi(\cdot) \|_{L^2(\Omega)}^2 + m_2 \| \nabla u(\cdot, T) - \nabla \psi(\cdot) \|_{L^2(\Omega)}^2 \\ &+ \mu_1 \| u(\cdot, 0) \|_{L^2(\Omega)}^2 + \mu_2 \| \nabla u(\cdot, 0) \|_{L^2(\Omega)}^2 \end{split}$$

Coronal brain slice Tumor at t = 0 (top) and t = T (bottom)

Brain with axial and sagittal slice Tumor at t = T

The initial state was reconstructed by iteratively minimizing E(u).



Various error measurements during the reconstruction process



LandweberNCG with L^2 -costNCG with $\dot{W}^{1,2}$ -costNCG with $W^{1,2}$ -costCell density at t = 0 as reconstructed for different cost functionals E(u)

Given a guesstimate of initial data u(x,0), the direct problem is solved. Then, the following well-posed *adjoint problem* is solved:

 $\begin{array}{ll} \partial_t \lambda(x,t) + \operatorname{div}(D(x) \nabla \lambda(x,t)) = f'_u(u(x,t))\lambda(x,t) & \text{ in } \Omega \times (0,T), \\ D(x) \nabla \lambda(x,t) \cdot n(x) = 0 & \text{ on } \partial \Omega \times (0,T), \\ \lambda(x,T) = (m_1 + \widetilde{m}_2 \Delta)(u(x,T) - \psi(x,T)) & \text{ in } \Omega, \end{array}$

Conclusion

• Finetuning regularization parameters allows faster convergence, while keeping numerical stability of the solution.

• Simulation with planted tumors shows potential for our approach.



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